

### **General Description**

The MAX5302 combines a low-power, voltage-output, 12-bit digital-to-analog converter (DAC) and a precision output amplifier in an 8-pin µMAX package. It operates from a single +5V supply, drawing less than 280µA of supply current.

The output amplifier's inverting input is available to the user, allowing specific gain configurations, remote sensing, and high output current capability. This makes the MAX5302 ideal for a wide range of applications, including industrial process control. Other features include a software shutdown and power-on reset.

The serial interface is SPI™/QSPI™/MICROWIRE™ compatible. The DAC has a double-buffered input, organized as an input register followed by a DAC register. A 16-bit serial word loads data into the input register. The DAC register can be updated independently or simultaneously with the input register. All logic inputs are TTL/CMOSlogic compatible and buffered with Schmitt triggers to allow direct interfacing to optocouplers.

# **Applications**

Industrial Process Control Automatic Test Equipment Digital Offset and Gain Adjustment Motion Control Remote Industrial Control Microprocessor-Controlled Systems

#### **Features**

- ♦ 12-Bit DAC with Configurable Output Amplifier
- ♦ +5V Single-Supply Operation
- ♦ Low Supply Current: 0.28mA Normal Operation 2µA Shutdown Mode
- ♦ Available in 8-Pin µMAX
- ♦ Power-On Reset Clears DAC Output to Zero
- ♦ SPI/QSPI/MICROWIRE Compatible
- ♦ Schmitt-Trigger Digital Inputs for Direct **Optocoupler Interface**

## **Ordering Information**

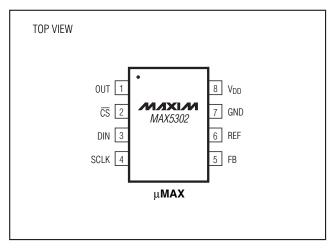
PART	TEMP. RANGE	PIN-PACKAGE
MAX5302CUA	0°C to +70°C	8 µMAX
MAX5302EUA	-40°C to +85°C	8 µMAX

# Functional Diagram

#### $V_{\text{DD}}$ REF GND FB OUT DAC DAC REGISTER CONTROL INPUT REGISTER MIXIMCS 16-BIT MAX5302 DIN SHIFT REGISTER SCLK

SPI and QSPI are trademarks of Motorola, Inc. MICROWIRE is a trademark of National Semiconductor Corp.

## Pin Configuration



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Maxim Integrated Products 1

### **ABSOLUTE MAXIMUM RATINGS**

V <sub>DD</sub> to GND	0.3V to +6V
REF, OUT, FB to GND	0.3V to (V <sub>DD</sub> + 0.3V)
Digital Inputs to GND	
Continuous Current into Any Pin	±20mA
Continuous Power Dissipation (TA = -	
8-Pin µMAX (derate 4.10mW/°C a	bove +70°C)330mW

0°C to +70°C
40°C to +85°C
+150°C
65°C to +150°C
+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **ELECTRICAL CHARACTERISTICS**

(Circuit of Figure 8,  $V_{DD}$  = +5V ±10%,  $V_{REF}$  = +2.5V,  $R_L$  = 5k $\Omega$ ,  $C_L$  = 100pF,  $T_A$  =  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A$  = +25°C. Output buffer connected in unity-gain configuration.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
STATIC PERFORMANCE—ANALOG SECTION						
Resolution	N		12			Bits
Differential Nonlinearity	DNL	Guaranteed monotonic			±1.0	LSB
Integral Nonlinearity (Note 1)	INL				±4	LSB
Offset Error	Vos			±0.3	±8	mV
Offset-Error Tempco	TCVos			6		ppm/°C
Gain Error (Note 1)	GE			-0.3	±3	LSB
Gain-Error Tempco				1		ppm/°C
Power-Supply Rejection Ratio	PSRR	4.5V ≤ V <sub>DD</sub> ≤ 5.5V			800	μV/V
REFERENCE INPUT						•
Reference Input Range	VREF		0	\	/ <sub>DD</sub> - 1.4	V
Reference Input Resistance	R <sub>REF</sub>	Code dependent, minimum at code 1554 hex	14	20		kΩ
MULTIPLYING-MODE PERFOR	RMANCE					-
Reference -3dB Bandwidth		$V_{REF} = 0.67Vp-p$		650		kHz
Reference Feedthrough		Input code = all 0s, V <sub>REF</sub> = 3.6Vp-p at 1kHz		-84		dB
Signal-to-Noise Plus Distortion Ratio	SINAD	V <sub>REF</sub> = 1Vp-p at 25kHz, code = full scale		77		dB
DIGITAL INPUTS						•
Input Voltage High	VIH		2.4			V
Input Voltage Low	V <sub>IL</sub>				0.8	V
Input Leakage Current	I <sub>IN</sub>	V <sub>IN</sub> = 0 or V <sub>DD</sub>		0.001	±0.5	μΑ
Input Capacitance	CIN			8		pF

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### **ELECTRICAL CHARACTERISTICS (continued)**

(Circuit of Figure 8,  $V_{DD}$  = +5V ±10%,  $V_{REF}$  = +2.5V,  $R_L$  = 5k $\Omega$ ,  $C_L$  = 100pF,  $T_A$  =  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A$  = +25°C. Output buffer connected in unity-gain configuration.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DYNAMIC PERFORMANCE			"			
Voltage Output Slew Rate	SR			0.6		V/µs
Output Settling Time		To $\pm 1/2$ LSB, $V_{STEP} = 2.5V$		14		μs
Output Voltage Swing		Rail-to-rail (Note 2)		0 to V <sub>DD</sub>		V
Current into FB				0.001	±0.1	μΑ
Start-Up Time				20		μs
Digital Feedthrough		$\overline{\text{CS}} = \text{V}_{\text{DD}},  \text{DIN} = 100 \text{kHz}$		5		nVs
POWER SUPPLIES			<u> </u>			ı
Supply Voltage	V <sub>DD</sub>		4.5		5.5	V
Supply Current	I <sub>DD</sub>	(Note 3)		0.28	0.4	mA
Supply Current in Shutdown		(Note 3)		4	20	μA
Reference Current in Shutdown				0.001	±0.5	μΑ
TIMING CHARACTERISTICS (Fi	gure 6)					
SCLK Clock Period	tcp		100			ns
SCLK Pulse Width High	tсн		40			ns
SCLK Pulse Width Low	tcL		40			ns
CS Fall to SCLK Rise Setup Time	tcss		40			ns
SCLK Rise to CS Rise Hold Time	tcsh		0			ns
DIN Setup Time	t <sub>DS</sub>		40			ns
DIN Hold Time	t <sub>DH</sub>		0			ns
SCLK Rise to CS Fall Delay	tcso		40			ns
CS Rise to SCLK Rise Hold Time	tcs1		40			ns
CS Pulse Width High	tcsw		100			ns

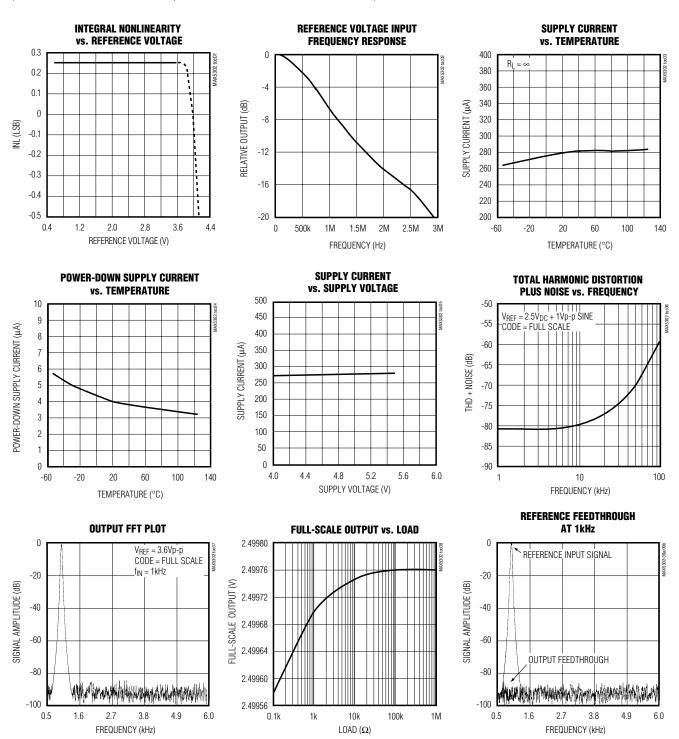
**Note 1:** Guaranteed from code 11 to code 4095 in unity-gain configuration.

Note 2: Accuracy is better than 1LSB for V<sub>OUT</sub> = 8mV to (V<sub>DD</sub> - 100mV), guaranteed by a power-supply rejection test at the end points.

**Note 3:**  $R_L = \infty$ , digital inputs at GND or  $V_{DD}$ .

# **Typical Operating Characteristics**

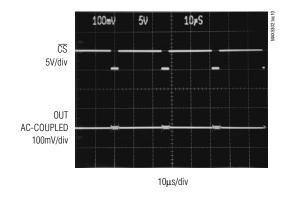
 $(V_{DD} = +5V, R_L = 5k\Omega, C_L = 100pF, T_A = +25^{\circ}C, unless otherwise noted.)$ 



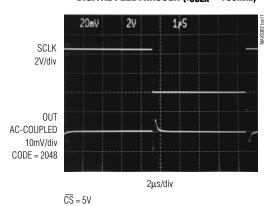
# **Typical Operating Characteristics (continued)**

 $(V_{DD} = +5V, R_L = 5k\Omega, C_L = 100pF, T_A = +25^{\circ}C, unless otherwise noted.)$ 

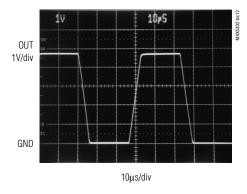
#### **MAJOR-CARRY TRANSITION**



#### DIGITAL FEEDTHROUGH (fSCLK = 100kHz)



#### **DYNAMIC RESPONSE**



GAIN = 2, SWITCHING FROM CODE 0 TO 4020

#### Pin Description

PIN	NAME	FUNCTION
1	OUT	DAC Output Voltage
2	CS	Chip-Select Input. Active low.
3	DIN	Serial-Data Input
4	SCLK	Serial-Clock Input
5	FB	DAC Output Amplifier Feedback
6	REF	Reference Voltage Input
7	GND	Ground
8	V <sub>DD</sub>	Positive Power Supply

## **Detailed Description**

The MAX5302 contains a voltage-output digital-to-analog converter (DAC) that is easily addressed using a simple 3-wire serial interface. The IC includes a 16-bit shift register, and has a double-buffered input composed of an input register and a DAC register (see *Functional Diagram*). In addition to the voltage output, the amplifier's negative input is available to the user.

The DAC is an inverted R-2R ladder network that converts a digital input (12 data bits plus 1 sub-bit) into an equivalent analog output voltage in proportion to the applied reference voltage. Figure 1 shows a simplified circuit diagram of the DAC.

#### Reference Inputs

The reference input accepts positive DC and AC signals. The voltage at the reference input sets the full-scale output voltage for the DAC. The reference input voltage range is 0 to ( $V_{DD}$  - 1.4V). The output voltage ( $V_{OUT}$ ) is represented by a digitally programmable voltage source, as expressed in the following equation:

where NB is the numeric value of the DAC's binary input code (0 to 4095), V<sub>REF</sub> is the reference voltage, and Gain is the externally set voltage gain.

The impedance at the reference input is code dependent, ranging from a low value of  $14k\Omega$  when the DAC has an input code of 1554 hex, to a high value exceeding several gigaohms (leakage currents) with an input code of 0000 hex. Because the input impedance at the reference pin is code dependent, load regulation of the reference source is important.

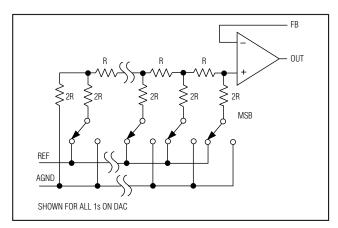


Figure 1. Simplified DAC Circuit Diagram

In shutdown mode, the MAX5302's REF input enters a high-impedance state with a typical input leakage current of 0.001µA.

The reference input capacitance is also code dependent and typically ranges from 15pF (with an input code of all 0s) to 50pF (at full scale).

The MAX873 +2.5V reference is recommended for the MAX5302

#### **Output Amplifier**

The MAX5302's DAC output is internally buffered by a precision amplifier with a typical slew rate of 0.6V/µs. Access to the output amplifier's inverting input provides the user greater flexibility in output gain setting/signal conditioning (see the *Applications Information* section).

With a full-scale transition at the MAX5302 output, the typical settling time to  $\pm 1/2 LSB$  is 14µs when loaded with 5k $\Omega$  in parallel with 100pF (loads less than 2k $\Omega$  degrade performance).

The amplifier's output dynamic responses and settling performances are shown in the *Typical Operating Characteristics*.

#### Shutdown Mode

The MAX5302 features a software-programmable shutdown that reduces supply current to a typical value of  $4\mu A$ . Writing 111X XXXX XXXX XXXX as the input control word puts the device in shutdown mode (Table 1).

In shutdown mode, the amplifier's output and the reference input enter a high-impedance state. The serial interface remains active. Data in the input registers is retained in shutdown, allowing the MAX5302 to recall the output state prior to entering shutdown. Exit shutdown mode by either recalling the previous configuration or

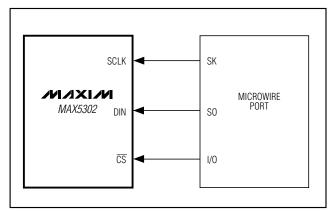


Figure 2. Connections for MICROWIRE

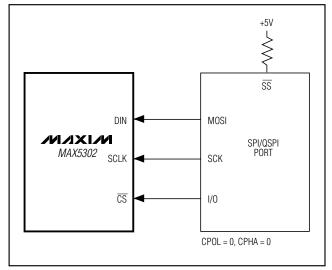


Figure 3. Connections for SPI/QSPI

by updating the DAC with new data. When powering up the device or bringing it out of shutdown, allow 20µs for the output to stabilize.

#### **Serial-Interface Configurations**

The MAX5302's 3-wire serial interface is compatible with both MICROWIRE (Figure 2) and SPI/QSPI (Figure 3). The serial-input word consists of 3 control bits followed by 12+1 data bits (MSB first), as shown in Figure 4. The 3-bit control code determines the MAX5302's response outlined in Table 1.

The MAX5302's digital inputs are double buffered. Depending on the command issued through the serial interface, the input register can be loaded without affecting the DAC register, the DAC register can be loaded directly, or the DAC register can be updated from the input register (Table 1).

#### **Serial-Interface Description**

The MAX5302 requires 16 bits of serial data. Table 1 lists the serial-interface programming commands. For certain commands, the 12+1 data bits are "don't cares." Data is sent MSB first and can be sent in two 8-bit packets or one 16-bit word ( $\overline{\text{CS}}$  must remain low until 16 bits are transferred). The serial data is composed of 3 control

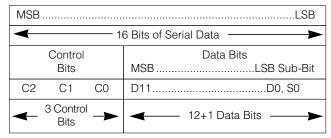


Figure 4. Serial-Data Format

## **Table 1. Serial-Interface Programming Commands**

16-BIT SERIAL WORD			RIAL WORD		
C2	C1	C0	D11D0 MSB LSB	S0	FUNCTION
Х	0	0	12 bits of data	0	Load input register; DAC register immediately updated (also exit shutdown).
Χ	0	1	12 bits of data	0	Load input register; DAC register unchanged.
Х	1	0	XXXXXXXXXX	Х	Update DAC register from input register (also exit shutdown; recall previous state).
1	1	1	XXXXXXXXXXX	Х	Shutdown
0	1	1	XXXXXXXXXXX	Х	No operation (NOP)

X = Don't care

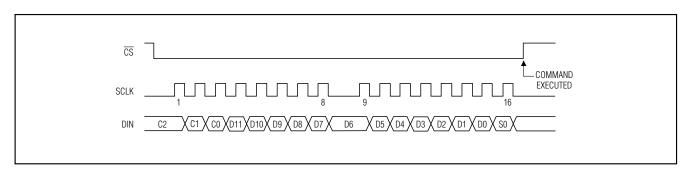


Figure 5. Serial-Interface Timing Diagram

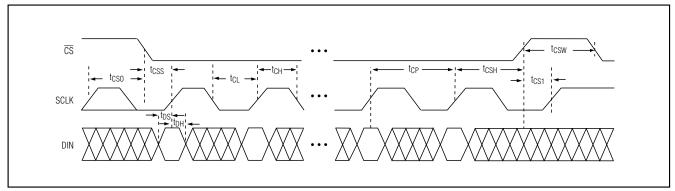


Figure 6. Detailed Serial-Interface Timing Diagram

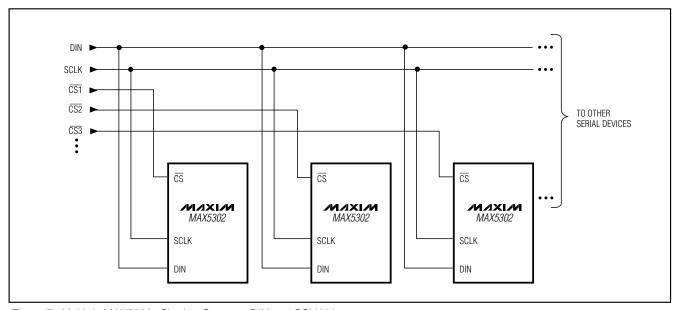


Figure 7. Multiple MAX5302s Sharing Common DIN and SCLK Lines

bits (C2, C1, C0), followed by the 12+1 data bits D11...D0, S0 (Figure 4). Set the sub-bit (S0) to zero. The 3-bit control code determines the register to be updated and the configuration when exiting shutdown.

Figures 5 and 6 show the serial-interface timing requirements. The chip-select  $(\overline{CS})$  pin must be low to enable the DAC's serial interface. When  $\overline{CS}$  is high, the interface control circuitry is disabled.  $\overline{CS}$  must go low at least toss before the rising serial-clock (SCLK) edge to properly clock in the first bit. When  $\overline{CS}$  is low, data is clocked into the internal shift register through the serial-data input pin (DIN) on SCLK's rising edge. The maximum guaranteed clock frequency is 10MHz. Data is latched into the MAX5302 input/DAC register on  $\overline{CS}$ 's rising edge.

Figure 7 shows a method of connecting several MAX5302s. In this configuration, the clock and the data bus are common to all devices, and separate chip-select lines are used for each IC.

# \_Applications Information

### **Unipolar Output**

For a unipolar output, the output voltage and the reference input have the same polarity. Figure 8 shows the MAX5302 unipolar output circuit, which is also the typical operating circuit. Table 2 lists the unipolar output codes.

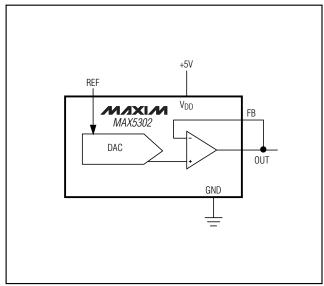


Figure 8. Unipolar Output Circuit

Figure 9 illustrates a Rail-to-Rail<sup>®</sup> output. This circuit shows the MAX5302 with the output amplifier configured with a closed-loop gain of +2 to provide a 0V to 5V full-scale range when a 2.5V reference is used.

#### **Bipolar Output**

The MAX5302 output can be configured for bipolar operation using Figure 10's circuit according to the following equation:

$$V_{OUT} = V_{REF} [(2NB / 4096) - 1]$$

where NB is the numeric value of the DAC's binary input code. Table 3 shows digital codes (offset binary) and the corresponding output voltage for Figure 10's circuit.

#### Using an AC Reference

In applications where the reference has AC-signal components, the MAX5302 has multiplying capability within the reference input range specifications. Figure 11 shows a technique for applying a sine-wave signal to the reference input where the AC signal is offset before being applied to REF. The reference voltage must never be more negative than GND.

The MAX5302's total harmonic distortion plus noise (THD+N) is typically less than -77dB (full-scale code), given a 1Vp-p signal swing and input frequencies up to 25kHz. The typical -3dB frequency is 650kHz, as shown in the *Typical Operating Characteristics* graphs.

Table 2. Unipolar Code Table

DAC CONTENTS MSB LSB	ANALOG OUTPUT
1111 1111 1111 (0)	$+V_{REF}\left(\frac{4095}{4096}\right)$
1000 0000 0001 (0)	$+V_{REF}\left(\frac{2049}{4096}\right)$
1000 0000 0000 (0)	$+V_{REF}\left(\frac{2048}{4096}\right) = \frac{+V_{REF}}{2}$
0111 1111 1111 (0)	$+V_{REF}\left(\frac{2047}{4096}\right)$
0000 0000 0001 (0)	$+V_{REF}\left(\frac{1}{4096}\right)$
0000 0000 0000 (0)	0V

Note: ( ) are for sub-bit.

Rail-to-Rail is a registered trademark of Nippon Motorola, Ltd.

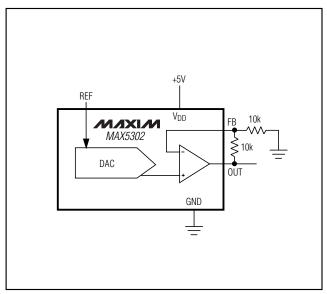


Figure 9. Unipolar Rail-to-Rail Output Circuit

### **Digitally Programmable Current Source**

The circuit of Figure 12 places an NPN transistor (2N3904 or similar) within the op amp feedback loop to implement a digitally programmable, unidirectional current source. The output current is calculated with the following equation:

where NB is the numeric value of the DAC's binary input code, and R is the sense resistor shown in Figure 12.

#### **Power-Supply Considerations**

On power-up, the input and DAC registers are cleared (set to zero code).

For rated MAX5302 performance,  $V_{REF}$  must be at least 1.4V below  $V_{DD}$ . Bypass  $V_{DD}$  with a 4.7 $\mu$ F capacitor in parallel with a 0.1 $\mu$ F capacitor to GND. Use short lead lengths and place the bypass capacitors as close to the supply pins as possible.

#### **Grounding and Layout Considerations**

Digital or AC transient signals on GND can create noise at the analog output. Connect GND to the highest-quality ground available.

Good PC board ground layout minimizes crosstalk between the DAC output, reference input, and digital input. Reduce crosstalk by keeping analog lines away from digital lines. Wire-wrapped boards are not recommended.

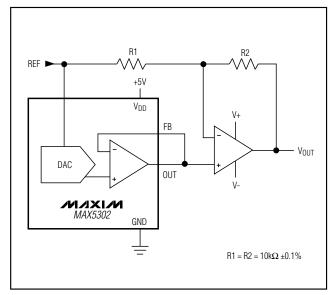


Figure 10. Bipolar Output Circuit

#### **Table 3. Bipolar Code Table**

DAC CONTENTS MSB LSB	ANALOG OUTPUT
1111 1111 1111 (0)	$+V_{REF}\left(\frac{2047}{2048}\right)$
1000 0000 0001 (0)	$+V_{REF}\left(\frac{1}{2048}\right)$
1000 0000 0000 (0)	OV
0111 1111 1111 (0)	$-V_{REF}\left(\frac{1}{2048}\right)$
0000 0000 0001 (0)	$-V_{REF}\left(\frac{2047}{2048}\right)$
0000 0000 0000 (0)	$-V_{REF}\left(\frac{2048}{2048}\right) = -V_{REF}$

Note: ( ) are for sub-bit.

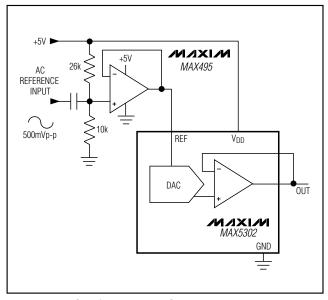


Figure 11. AC Reference Input Circuit

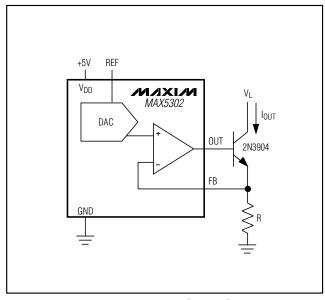


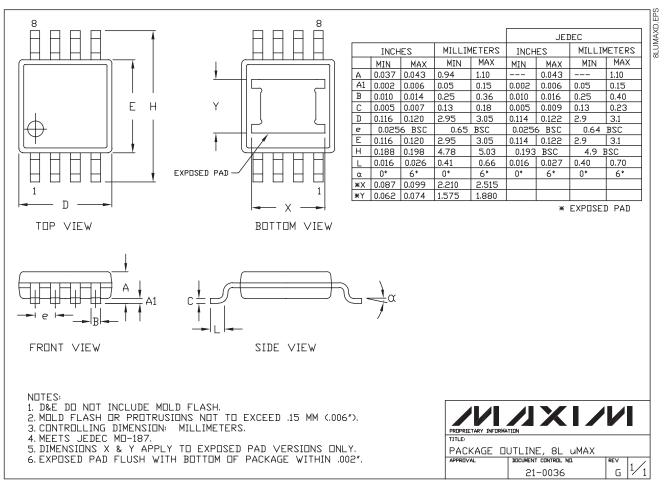
Figure 12. Digitally Programmable Current Source

# \_ Chip Information

TRANSISTOR COUNT: 3053

SUBSTRATE CONNECTED TO AGND

# **Package Information**



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